AU-105

# B.Sc. Part—II (Semester—IV) Examination MATHEMATICS

## Paper-VIII

(Classical Mechanics)										
Time	e : T	hree	[Maximum Marks: 60							
Note: -(1) Question No. 1 is compulso			Question No. 1 is compulsory and att	empt it	once only,					
		(2)	Solve one question from each unit.							
1.	Cho	ose t	he correct alternative :							
	(i)	If th	e equation of constraint varies with ti	it is called as:						
		(a)	Holonomic constraint							
		(b)	Stationary or seleronomous constraint							
		(c)	Moving or Rheonomous constraint							
		(d)	None of these		1					
	(ii)	The	polar equation of a conic section is							
			$\frac{\ell}{r} = 1 + e \cos (\theta - \theta_0)$							
		whe	city.							
		If e	< 1, then conic represents							
		(a)	Hyperbola	(b)	Parabola					
		(c)	Circle	(d)	Ellipse					
	(iii)	If the function $f(x)$ has maximum or minimum value at some point $x = x_0$ , the point $x = x_0$ is called as								
		(a)	Stationary point	(b)	Critical point					
		(c)	Extremum point	(d)	None of these 1					
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(iv)	The	shortest distance between two points in a	spac	ce is				
		A circle		A straight line				
	(c)	An ellipse	(d)	A parabola	l			
(v)	Fun	ections $y(x)$ for which $\delta I[y(x)] = 0$ are call	led _					
	(a)	Admissible functions	(b)	Absolute functions				
		Stationary functions	- '	None of these	1			
(vi)	H is the Hamiltonian of the system then a generalized coordinate $q_i$ is said to be cyclic							
	if _							
		∂H		∂Н				
	(a)	$\frac{\partial H}{\partial q_i} \neq 0$	(b)	$\frac{\partial H}{\partial q_i} > 0$				
		11		oq <sub>i</sub>				
	(0)	$\frac{\partial H}{\partial q_i} = 0$	(4)	$\frac{\partial H}{\partial a} < 0$	1			
	(c)	$\partial  ext{q}_i$	(a)	$\partial q_i$	1			
(vii)	) If a	. 3×3 matrix A is a rotation matrix, then A	is o	rthogonal and .				
		$ \Lambda  = 0$		A   ≠ 1				
		A   = 1	(d)	None of these	1			
(viii)		number of degrees of freedom for a motion	, ,		ar			
(*111)	1110	mander of degrees of freedom for a mone	JII 01	a partiere along a straight inte	CII.			
	(a)	·	(b)	1				
					1			
	(c)	2	(d)	3	1			
(ix)	If F	I is the Hamiltonian of the system and p	_ = -	$\frac{\partial L}{\partial q_i}$ is the generalized moment	un			
	asso	ociated with generalized coordinate q, ther	the	Hamilton's equations are				
		∂H <u>.</u> ∂Π <u>.</u>		∂Н <u>.</u> ∂Н <u>.</u>				
	(a)	$\frac{\partial \mathbf{H}}{\partial \mathbf{p}_{i}} = \dot{\mathbf{q}}_{i},  \frac{\partial \mathbf{H}}{\partial \mathbf{q}_{i}} = \dot{\mathbf{p}}_{i}$	(b)	$\frac{\partial H}{\partial p_i} = -\dot{q}_i ,  \frac{\partial H}{\partial q_i} = \dot{p}_i$				
		211 211		211 211				
	(c)	$\frac{\partial H}{\partial \mathbf{p}_{i}} = \dot{\mathbf{q}}_{i} \cdot \frac{\partial H}{\partial \mathbf{q}_{i}} = -\dot{\mathbf{p}}_{i}$	(d)	$\frac{\partial H}{\partial p_i} = -\dot{q}_i,  \frac{\partial H}{\partial q_i} = -\dot{p}_i$	1			
		$\mathcal{O}p_{\scriptscriptstyle 1} \qquad \mathcal{O}q_{\scriptscriptstyle 1}$	` ′	$op_i$ , $oq_i$				
(x)	For	a particle moving under a central force	such	that $V = kr^{n+1}$ , the virial theor	en			
	redu	uces to						
	(a)	$\overline{T} = (n+1)\overline{V}$	(b)	$\overline{T} = (n-1)\overline{V}$				
	(c)	$2\overline{T} = (n-1)\overline{V}$	(d)	$2\overline{T} = (n+1)\overline{V}$	1			
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#### UNIT-I

- 2. (a) Derive the Lagrange's equations of motion in the form  $\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \right) \frac{\partial L}{\partial \dot{q}_i} = 0$ , i = 1, 2,...,n for conservative system from D'Alembert's principle.
  - (b) Construct a Lagrangian for a spherical pendulum and obtain the Lagrange's equations of motion.

#### OR

- 3. (p) Use D'Alembert's principle to obtain the equations of motion of a simple pendulum.
  - (q) Two particles of masses  $m_1$  and  $m_2$  are connected by a light inextensible string which passes over a small smooth fixed pulley. If  $m_1 > m_2$ , then show that the common

acceleration of the particles is 
$$\frac{(m_1 - m_2)}{(m_1 + m_g)}g$$
.

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### UNIT-II

- (a) State and prove Virial theorem.
  - (b) Show that if a particle describes a circular orbit under the influence of an attractive central force directed towards point on the circle then the force varies as the inverse fifth power of the distance.

#### OR

- 5. (p) Prove that in a central force field, the areal velocity is conserved.
  - (q) Prove that if the potential energy is a homogeneous function of degree -1 in the radius vector \(\bar{t}\_i\), then the motion of a conservative system takes place in a finite region of space only if the total energy is negative.

#### UNIT—III

6. (a) Find the extremals of 
$$I[y(x)] = \int_a^b [y^2 + y'^2 + 2ye^x]dx$$
.

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(b) Show that the functional:

$$I[y(x)] = \int_{0}^{1} [2y(x) + y'(x)]dx$$

defined in the space  $C_1[0, 1]$  is continuous on the function  $y_0(x) = x$  in the sense of first order proximity.

#### OR

- 7. (p) Prove that if x does not occur explicitly in F then,  $F_y y' F = constant$ .
  - (q) Find the extremals of the functional:

$$I[y(x)] = \int_{0}^{\log_2} (e^{-x}y'^2 - e^xy^2) dx.$$
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#### UNIT-IV

- (a) Obtain the Hamiltonian and then deduce the equations of motion for a simple pendulum.
  Show that the Hamiltonian of the system is the total energy and also the constant of motion.
  - (b) A particle moves on a smooth surface under gravity. Use Hamilton's principle to show that the equations of motion are:

$$\ddot{\mathbf{x}} = \ddot{\mathbf{y}} = 0, \ \ddot{\mathbf{z}} = -\mathbf{g}$$

where the vertical is taken along the z-axis.

#### OR

- 9. (p) Define: Hamiltonian H. Derive the Hamilton's equations or the canonical equations of Hamilton.
  - (q) Use Hamilton's principle to find the equations of motion of a particle of mass moving in space in a conservative force field F.

#### UNIT-V

- 10. (a) Describe the frame rotation and obtain the rotation matrix.
  - (b) If  $A_1 = I + \epsilon_1$  and  $A_2 = I + \epsilon_2$  be two infinitesimal rotations, then prove that infinitesimal rotations commute.

#### OR

- 11. (p) Prove that if A is any  $2\times 2$  orthogonal matrix with determinant |A| = 1, then A is a rotation matrix.
  - (q) If  $A = I + \epsilon$ , then prove that the inverse rotation matrix is  $A^{-1} = I \epsilon$ .

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